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#include <stdio.h>
#include <string.h>
#include <ctype.h>

#include "freertos/FreeRTOS.h"
#include "freertos/event_groups.h"

#include "esp_wifi.h"
#include "esp_system.h"
#include "esp_event.h"
#include "esp_event_loop.h"
#include "esp_log.h"
#include "driver/spi_master.h"
#include "soc/gpio_struct.h"
#include "driver/gpio.h"

#include "mfrc.h"
// #include "network.h" // for myEventGroup ...
#include "spi.h"
#include "heap_alloc_caps.h"

static const char *TAG = "SPI";

typedef struct {
    TaskHandle_t      xHandle;
    spi_device_handle_t spi;
    spi_config_t      *config;
    int               dc;      // current value of D/C
} pvSPI_t;

static int
spi_transfer(pvSPI_t *pv, char *data, int len, int dc)
{
    esp_err_t ret;
    spi_transaction_t trans, *t = &trans;
    char recvbuff[16];

    ESP_LOGI(TAG, "spi_transfer: entered");
    ESP_LOGI(TAG, "\tdata=%p 0x%02x len=%d, dc=%d", data,
data[0], len, dc);
    ESP_LOGI(TAG, "pv=%p", pv);
    ESP_LOGI(TAG, "\tdevice='%s'", pv->config->devname);

    memset(t, 0, sizeof(spi_transaction_t)); // Zero out the
transaction
    // t->command = data[0];
    // t->flags = SPI_TRANS_MODE_DIO;
    t->length = len * 8; // len is in bytes, length is in
bits
    if(len <= 4) {
        ESP_LOGI(TAG, "doing short xmit");
        t->flags = SPI_TRANS_USE_TXDATA;
        t->tx_data[0] = data[0];
    }
}

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        else
            t->tx_buffer = data;
            pv->dc = dc;
            ESP_LOGI(TAG, "calling spi_device_transmit ...");
            ret = spi_device_transmit(pv->spi, t); //Transmit!
            ESP_LOGI(TAG, "\tret=%d", ret);
            return ret == ESP_OK;
    }

    /*
    | This function is called (in irq context!) just before a
    transmission starts. It will
    | set the D/C line to the value indicated in the user field.
    */
    static void
    _spi_pre_transfer_callback(spi_transaction_t *t)
    {
        pvSPI_t *pv= (pvSPI_t *) t->user;
        ESP_LOGI(TAG, "_spi_pre_transfer_callback: %d->%d", pv->config-
        >pins[gpio_DC], pv->dc);

        gpio_set_level(pv->config->pins[gpio_DC], pv->dc);
    }

    static int
    dev_spi_init(void *pvParams)
    {
        pvSPI_t *pv = pvParams;
        ESP_LOGI(TAG, "dev_spi_init: rst pin is: %d", pv->config-
        >pins[gpio_RST]);

        /*
        | toggle the reset
        */
        if(pv->config->pins[gpio_RST] != -1) {
            gpio_set_level(pv->config->pins[gpio_RST], 0);
            msDelay(100);
            gpio_set_level(pv->config->pins[gpio_RST], 1);
            msDelay(100);
        }

        return 0;
    }

    static void
    spiTask(void *pvParams)
    {
        pvSPI_t *pv = pvParams;

        ESP_LOGI(TAG, "spiTask: entered for device: %s", pv->config-
        >devname);

        while(dev_spi_init(pv) != 0) {

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        ESP_LOGE(TAG, "failed to init device '%s'", pv->config-
>devname);
        msDelay(5000);
    }

    ESP_LOGI(TAG, "spiTask: '%s': init ok", pv->config->devname);

    for(;;) {
        msDelay(10000);
    }
}

void *
spiInit(spi_config_t *config)
{
    pvSPI_t    *pv;

    esp_log_level_set(TAG, ESP_LOG_DEBUG);
    ESP_LOGI(TAG, "spiInit: entered");

    pv = calloc(1, sizeof(pvSPI_t));
    if(pv == NULL) {
        ESP_LOGE(TAG, "no memory available!");
        goto bad;
    }

    pv->config = config;

    esp_err_t ret;
    spi_bus_config_t buscfg = {
        .quadwp_io_num    = -1,
        .quadhd_io_num    = -1
    };
    buscfg.miso_io_num = config->pins[gpio_MISO];
    buscfg.mosi_io_num = config->pins[gpio_MOSI];
    buscfg.sclk_io_num = config->pins[gpio_CLK];

    spi_device_interface_config_t devcfg = {
        //.command_bits = 8,
        //.address_bits = 64,
        .clock_speed_hz    = 10000000,    // Clock out at 10
MHz
        .mode              = 0,            // SPI mode 0
        .queue_size        = 7,            // We want to be
able to queue 7 transactions at a time
        .pre_cb            = _spi_pre_transfer_callback,
    };
    devcfg.spics_io_num = config->pins[gpio_CS];
    /*
    | Initialize the SPI bus
    */
    ret = spi_bus_initialize(HSPI_HOST, &buscfg, 1);
    if(ret != ESP_OK) {
        ESP_LOGE(TAG, "spi_bus_initialize failed: %d", ret);
    }
}

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        goto bad;
    }
    /*
    | Attach the device to the SPI bus
    */
    ret = spi_bus_add_device(HSPI_HOST, &devcfg, &pv->spi);
    if(ret != ESP_OK) {
        ESP_LOGE(TAG, "spi_bus_add device failed: %d", ret);
        goto bad;
    }

    BaseType_t err = xTaskCreate(&spiTask, "spiTask",
                                configMINIMAL_STACK_SIZE,
                                (void *)pv,
                                5, // priority
                                &pv->xHandle);

    if(err != pdPASS) {
        ESP_LOGE(TAG, "failed to create task!");
    bad:
        if(pv)
            free(pv);
        return NULL;
    }
    /*
    | Initialize non-SPI GPIOs
    */
    if(config->pins[gpio_DC] != -1)
        gpio_set_direction(config->pins[gpio_DC],
GPIO_MODE_OUTPUT);
    if(config->pins[gpio_RST] != -1)
        gpio_set_direction(config->pins[gpio_RST],
GPIO_MODE_OUTPUT);

    ESP_LOGI(TAG, "spiInit OK");

    return (void *)pv;
}

int
spiCmd(void *pv, char cmd)
{
    int res;

    // make sure DC is 0/low
    res = spi_transfer(pv, &cmd, 1, 0);
    return res;
}

int
spiDat(void *pv, char *data, int len)
{
    // make sure DC is 1/high
    return spi_transfer(pv, data, len, 1);
}

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}  
  
#include "ssd1306.h"  
int  
spiTest()  
{  
    return ssd1306Test();  
}
```